

→ Conservation Laws in MHD

- here discuss: conservation $\left\{ \begin{array}{l} \text{momentum} \\ \text{energy} \\ \text{angular momentum} \end{array} \right.$

and virial theorems

→ Momentum → key: construct evolution of momentum density

have:
$$\rho \left(\frac{\partial \underline{v}}{\partial t} + \underline{v} \cdot \nabla \underline{v} \right) = - \nabla \cdot \left(p + \frac{\underline{B}^2}{8\pi} \right) + \frac{\underline{B} \cdot \nabla \underline{B}}{4\pi} + \rho \underline{g}$$

body force

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{v}) = 0$$

$$\Rightarrow \frac{\partial (\rho \underline{v})}{\partial t} + \nabla \cdot \left(\rho \underline{v} \underline{v} \right) = - \nabla \cdot \left(p + \frac{\underline{B}^2}{8\pi} \right) + \frac{\nabla \cdot \underline{B} \underline{B}}{4\pi} + \rho \underline{g}$$

$\frac{\partial (\rho \underline{v})}{\partial t}$ momentum density
 $\nabla \cdot (\rho \underline{v} \underline{v})$ Reynolds stress tensor
 $\underline{T}_R = \rho \underline{v} \underline{v}$
 $\frac{\nabla \cdot \underline{B} \underline{B}}{4\pi}$ Maxwell stress tensor
 $\underline{T}_B = \frac{\underline{B}^2}{8\pi} \underline{I} - \frac{\underline{B} \underline{B}}{4\pi}$

thus re-write:

$$\frac{\partial (\rho \underline{v})}{\partial t} = - \nabla \cdot \underline{T} + \rho \underline{g}$$

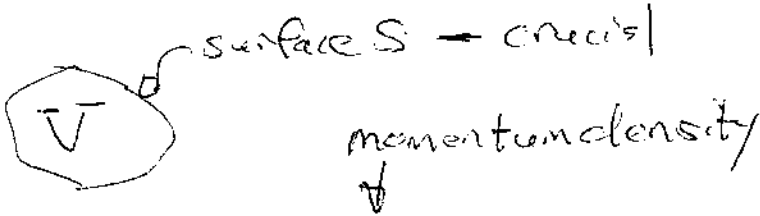
where

$$\underline{\underline{T}} = \left(\rho + \frac{B^2}{8\pi} \right) \underline{\underline{I}} + \frac{B_i B_j}{4\pi} - \rho \underline{v} \underline{v}$$

$$T_{ij} = \left(\rho + \frac{B^2}{8\pi} \right) \delta_{ij} + \frac{B_i B_j}{4\pi} - \rho v_i v_j$$

↪ also Gaussian surface

Then, if consider a 'blob' of $\left\{ \begin{array}{l} \text{plasma} \\ \text{magneto fluid} \end{array} \right\}$:



$$\frac{\partial \underline{p}}{\partial t} = \int d^3x \frac{\partial (\rho \underline{v})}{\partial t}$$

↓
momentum



blob enclosed by arbitrary, non-dynamical surface.

$$= - \int d^3x \nabla \cdot \underline{\underline{T}} + \int d^3x \rho \underline{g}$$

↪ net body force

$$= \int d\underline{s} \cdot \underline{\underline{T}} + \int d^3x \rho \underline{g}$$

So, apart from volume integrated body force,

$$\frac{\partial \underline{p}}{\partial t} = - \int d\underline{s} \cdot \underline{\underline{T}}$$

{ change in momentum set by stress on surface of blob

$$\underline{\underline{T}} = \left(\rho + \frac{B^2}{8\pi} \right) \underline{\underline{I}} - \frac{B_i B_j}{4\pi} + \rho \underline{v} \underline{v}$$

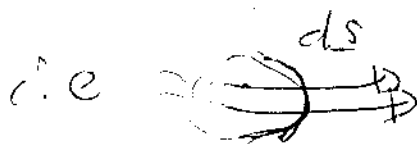
Thus, can identify ways momentum is lost by the blob:

$$-\underline{T}_{\underline{R}} \cdot d\underline{S} = -\rho \underline{V} \underline{V} \cdot d\underline{S} \quad \rightarrow \text{flux of momentum density thru surface}$$

$$-\underline{T}_{\rho} \cdot d\underline{S} = -\left(\rho + \frac{B^2}{8\pi}\right) \cdot d\underline{S} \quad \rightarrow \text{pressure (total) force on surface, in } -d\underline{S} \text{ direction}$$

$$-\underline{T}_{\text{Mag ten}} \cdot d\underline{S} = \frac{\underline{B} \underline{B} \cdot d\underline{S}}{4\pi} \quad \rightarrow \text{magnetic tension force in } +\underline{B} \text{ direction, piercing surface}$$

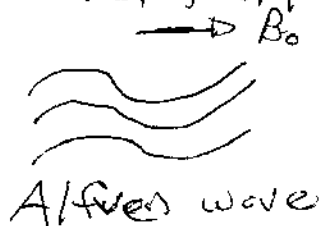
\rightarrow tension of $\frac{B}{4\pi}$,
 $\sim (\underline{B} \cdot d\underline{S}) \frac{B}{4\pi}$,
 # of lines thru $d\underline{S}$ outward
 per line



\rightarrow Note that magnetic tension is independent of sign of \underline{B} (as it should, tension is strictly speaking, a dyad $\begin{matrix} \uparrow \\ \downarrow \end{matrix}$, not \uparrow)

\hookrightarrow tensor field $\sim \underline{B} \underline{B}$

\rightarrow can make obvious analogy between 'Strings' and field lines

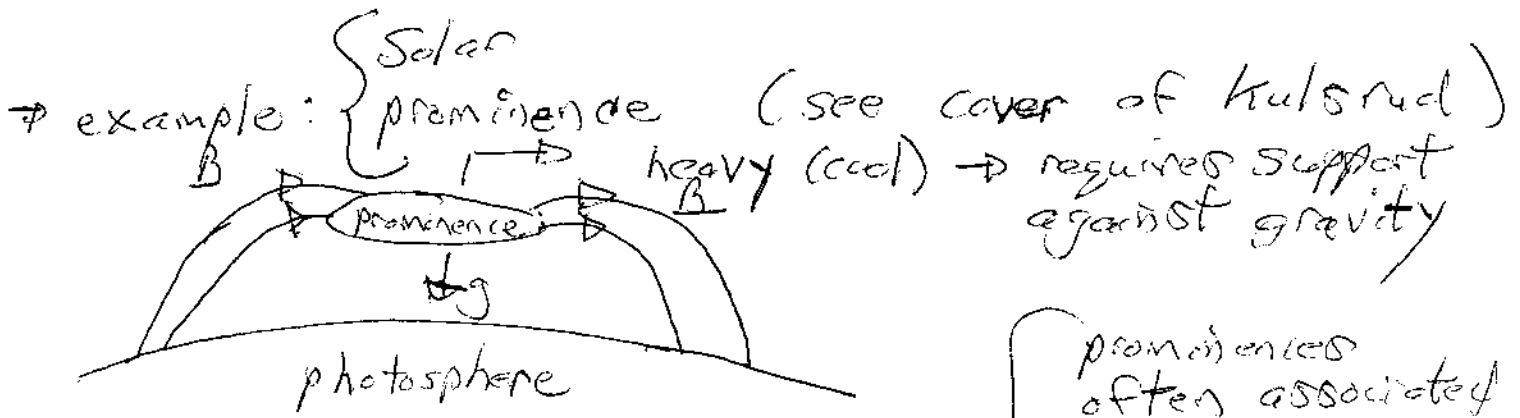


$$\# \text{ strings/area} = B$$

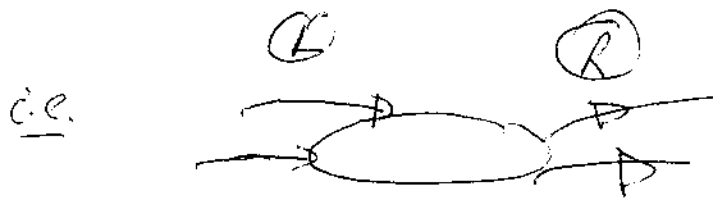
$$\nabla = c/B \rightarrow \text{mass per length of string}$$

$$T = B/4\pi$$

$$\begin{aligned} v_{ph}^2 &= T/\nabla \\ &= B^2/4\pi \rho \\ &= v_A^2 \end{aligned}$$



prominences often associated with radiative condensation



$L \Rightarrow \# \text{lines/area} = \underline{B} \cdot \underline{dS} < 0$ (inward)

force/line is toward

$\therefore \underline{F}_L \rightarrow$ toward upper left

$R \Rightarrow \# \text{lines/area} = \underline{B} \cdot \underline{dS} > 0$

f/line is toward upper right

$\underline{F}_R \rightarrow$ toward upper right

this → prominence supported by magnetic tension (aka hammock—string)
 → squashing \underline{B} → support by magnetic pressure, too

→ The Skeptic: "what of EM Momentum?"

$$\underline{P}_{EM} = \underline{E} \times \underline{B} / 4\pi c$$

$$E \sim \frac{vB}{c} \Rightarrow \rho_{EM} \sim (\rho v) \frac{B^2}{4\pi c^2} \\ \sim \rho v \left(\frac{v_A^2}{c^2} \right) \ll 1$$

N.B. obviously important in relativistic and EMHD

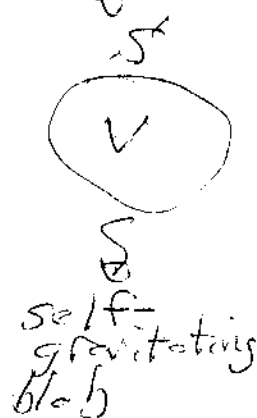
For $v_A \ll c$.

→ Angular Momentum → need Kelvinoid --- "virtual surface"

→ Energy kinetic thermal magnetic gravity

$$\text{Now energy: } E = E_v + E_p + E_B + E_g$$

$$E = \int_V d^3x \left[\frac{1}{2} \rho v^2 + \frac{p}{\gamma-1} + \frac{B^2}{8\pi} + \frac{\rho \phi}{2} \right]$$



where $\underline{g} = -\nabla \phi$

$$\nabla^2 \phi = 4\pi G \rho \quad \text{c.e. } \underline{g} \text{ evolves self-consistently (not "constant")}$$

N.B. Problem: Jeans Instability

→ Calculate the growth rate of density perturbations in an un-magnetized, self-gravitating fluid

→ repeat in 1D using Vlasov equation

→ Where does E_p come from?

Consider work to compress plasma/fluid, i.e.

$$dW = -p dV$$

$$\Delta E = - \int_0^{p_0} p(\rho) d(1/\rho) = \int_0^{p_0} \left(\frac{p}{\rho_0}\right)^\gamma \rho_0 \frac{dp}{\rho^2}$$

$$= \frac{p_0}{\rho_0(\gamma-1)} \Rightarrow \epsilon = \rho_0 \Delta E = \frac{p_0}{(\gamma-1)}$$

↓
energy density

→ for energy balance, crank it out, using MHD equations

$$\frac{dE}{dt} = \frac{dE_v}{dt} + \frac{dE_p}{dt} + \frac{dE_B}{dt} + \frac{dE_g}{dt}$$

$$\textcircled{1} \quad \frac{d}{dt} E_v = \int d^3x \frac{\partial}{\partial t} \left(\frac{\rho v^2}{2} \right)$$

$$= \int d^3x \left[v^2 \frac{\partial \rho}{\partial t} + \rho \frac{\partial v}{\partial t} \cdot v \right] d^3x$$

→ if ρ leaves S.T. and cancels 2nd.

$$= \int d^3x \left[-\frac{v^2}{2} \nabla \cdot (\rho v) - v \cdot \rho (v \cdot \nabla v) - v \cdot \nabla p + v \cdot (\nabla \times B) - \rho v \cdot \nabla \phi \right]$$

$$\frac{d}{dt} \int -\frac{v^2}{2} \rho(\underline{v}) = -\frac{v^2}{2} \rho \Big| + \int (\underline{v} \cdot \nabla \underline{v}) \cdot \rho \underline{v} \quad 30\%$$

\downarrow
 cancels 2nd term in $\frac{dE_v}{dt}$

$$\textcircled{2} \quad \frac{d}{dt} E_p = \int \frac{d^3x}{\gamma-1} \frac{\partial p}{\partial t}$$

Now eqn. state $\Rightarrow \frac{1}{\rho} \frac{dp}{dt} + \frac{\gamma}{\rho} \frac{dp}{dt} = 0$

and $\frac{1}{\rho} \frac{dp}{dt} = -\underline{v} \cdot \underline{\nabla}$ $\left[\frac{1}{(\rho/\rho_0)} \frac{d}{dt} (\rho/\rho_0) = 0 \right]$

$$\Rightarrow \frac{\partial p}{\partial t} = -\underline{v} \cdot \nabla p - \gamma p \underline{\nabla} \cdot \underline{v}$$

$$\text{So } \frac{d}{dt} E_p = \frac{-1}{(\gamma-1)} \int d^3x (\underline{v} \cdot \nabla p + \gamma p \underline{\nabla} \cdot \underline{v})$$

$$= - \int d^3x \left[\frac{\gamma}{\gamma-1} \nabla \cdot (\rho \underline{v}) - \underline{v} \cdot \nabla p \right]$$

\int
yields a surface term

\int
cancels $\underline{v} \cdot \nabla p$ term in $\frac{dE_v}{dt}$

expect similar relation between $\underline{J} \times \underline{B}$ and $\frac{\partial B^2}{\partial t} \dots$

$$\textcircled{3} \quad \frac{d}{dt} E_B = \frac{1}{4\pi} \int d^3x \underline{B} \cdot \frac{\partial \underline{B}}{\partial t}$$

$$= \frac{1}{4\pi} \int d^3x \underline{B} \cdot (\underline{\nabla} \times \underline{V} \times \underline{B}) \quad \text{by induction eqn.}$$

$$= - \int d^3x \left\{ \underbrace{\underline{\nabla} \cdot \left[\frac{\underline{B} \times (\underline{V} \times \underline{B})}{4\pi} \right]}_{\substack{\text{surface term} \\ (\rightarrow \text{Poynting})}} - \underbrace{\frac{(\underline{\nabla} \times \underline{B}) \cdot (\underline{V} \times \underline{B})}{4\pi}}_{\substack{\downarrow \\ \underline{J} \cdot \underline{V} \times \underline{B}}} \right\}$$

$$\underline{J} = \int d^3x \underline{J} \cdot (\underline{V} \times \underline{B}) = - \int d^3x (\underline{J} \times \underline{B}) \cdot \underline{V}$$

\downarrow
cancels $\underline{V} \cdot \underline{J} \times \underline{B}$ term
in dE_B/dt

Which leaves:

$$\textcircled{4} \quad \frac{dE_g}{dt} = \frac{1}{2} \int d^3x \left(\phi \frac{\partial \rho}{\partial t} + \rho \frac{\partial \phi}{\partial t} \right)$$

$$= \frac{1}{2} \int d^3x \phi \frac{\partial \rho}{\partial t} + \int d^3x \frac{\nabla^2 \phi}{8\pi G} \frac{\partial \phi}{\partial t}$$

cibp \Rightarrow

$$= \frac{1}{2} \int d^3x \phi \frac{\partial \rho}{\partial t} d^3x + \int \frac{\phi \nabla^2 \phi}{8\pi G} d^3x$$

$$\begin{aligned}
\frac{dE_g}{dt} &= \frac{1}{2} \int \phi \frac{\partial \rho}{\partial t} d^3x + \frac{1}{2} \int d^3x \phi \frac{\partial \rho}{\partial t} \\
&= \int d^3x \phi \frac{\partial \rho}{\partial t} = - \int d^3x \phi \nabla \cdot (\rho \underline{v}) \\
&= + \int d^3x \rho \underline{v} \cdot \nabla \phi \\
&\quad \left. \begin{array}{l} \text{cancels} \\ -\rho \underline{v} \cdot \nabla \phi \text{ in } \frac{dE_H}{dt} \end{array} \right\} \quad + \int d\underline{s} \cdot \rho \underline{v} \cdot \underline{v}
\end{aligned}$$

Note: $-\underline{v} \cdot \nabla A$; $\underline{v} \cdot (\underline{J} \times \underline{B})$; $-\rho \underline{v} \cdot \nabla \phi$; $\underline{v} \cdot \rho \underline{v} \cdot \underline{v}$
 terms all cancel in $\frac{dE_g}{dt}$!

Now adding up all 4 pieces \Rightarrow

$$\frac{dE}{dt} = - \int d\underline{s} \cdot \left[\rho \underline{v} \frac{v^2}{2} + \frac{\gamma}{\gamma-1} \rho \underline{v} - \frac{(\underline{v} \times \underline{B}) \times \underline{B}}{4\pi} + \rho \underline{v} \phi \right]$$

i.e. not surprisingly, only survivors are surface terms... \Rightarrow in ideal MHD, only change in energy of blob involves boundary...

i.e. have:

$$\frac{dE}{dt} = - \int d\mathbf{S} \cdot \left[\overset{\textcircled{1}}{\rho \mathbf{V} \frac{V^2}{2}} + \overset{\textcircled{2}}{\frac{\gamma \rho \mathbf{V}}{\gamma-1}} - \overset{\textcircled{3}}{\frac{(\mathbf{V} \times \mathbf{B}) \times \mathbf{B}}{4\pi}} + \overset{\textcircled{4}}{\rho \mathbf{V} \phi} \right]$$

① \rightarrow kinetic energy loss via simple kinetic energy flow thru surface.

② $\rightarrow - \frac{\gamma \mathbf{V} \cdot d\mathbf{S}}{\gamma-1} \rho \rightarrow$ outward flow of enthalpy

i.e. $-\frac{\gamma \rho \mathbf{V} \cdot d\mathbf{S}}{\gamma-1} = -\frac{\rho}{\gamma-1} \mathbf{V} \cdot d\mathbf{S} - \rho \mathbf{V} \cdot d\mathbf{S}$

why the $\gamma \rho$ \rightarrow

\downarrow
outward flow of thermal energy
($d\mathbf{S} \cdot \mathbf{V} \frac{\rho}{\gamma-1}$) thus

\downarrow
pdV work of blob on exterior

③ as $\underline{\underline{E}} = -\frac{\mathbf{V} \times \mathbf{B}}{c} \rightarrow$

so ③ = $d\mathbf{S} \cdot \frac{\underline{\underline{E}} \times \mathbf{B}}{4\pi c} \rightarrow$ $\left. \begin{array}{l} \text{loss of} \\ \text{energy by} \\ \text{Poynting flux} \end{array} \right\}$

④ loss of gravitational potential energy due outflow from blob ...
It's all clear!!!

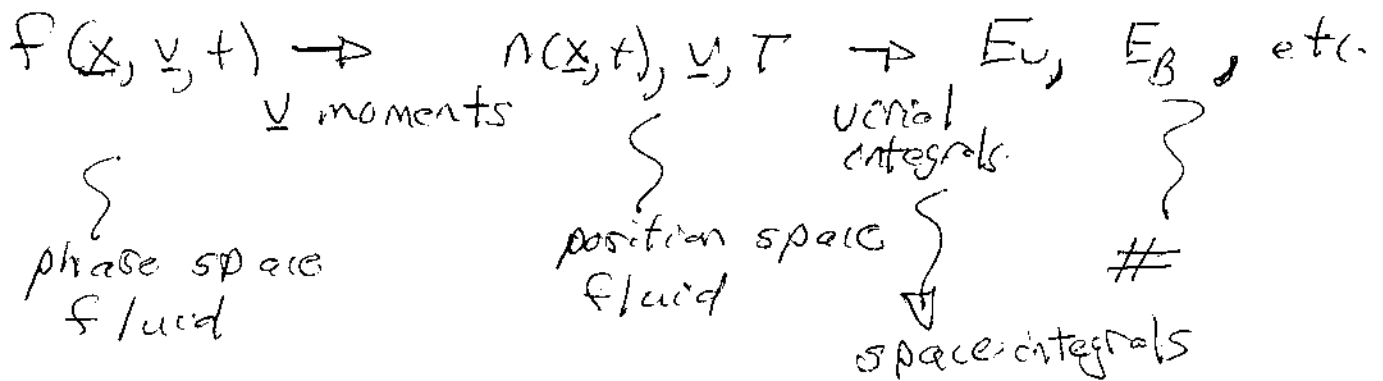
this brings us to

→ Virial Theorems in MHD

- what is a virial theorem
- why yet another theorem?

→ Virial Theorems are:

- space/time averaged energy theorems
- "lumped parameter" relations for energies in complex, multi-element interacting systems
- useful for 'back-of-envelope' estimates, etc.
- logically extend the moment program:



Before proceeding:

Can an isolated blob of MHD plasma confine itself without self gravity?

Easily answered by Virial Theorem. ...

Recall, for system of particles, Virial theorem derived by considering:

$$\begin{aligned} \frac{d}{dt} \left(\sum_i \underline{p}_i \cdot \underline{x}_i \right) &= \sum_i \underline{p}_i \cdot \underline{\dot{x}}_i + \sum_i \dot{\underline{p}}_i \cdot \underline{x}_i \\ &= \underbrace{2T}_{\text{kinetic energy}} + \sum_i \left(-\frac{\partial U}{\partial \underline{x}_i} \right) \cdot \underline{x}_i \\ &\quad \underbrace{\text{via Newton's Law}} \end{aligned}$$

Now, if $\sum_i \underline{p}_i \cdot \underline{x}_i$ bounded,

$$\left\langle \frac{d}{dt} \sum_i \underline{p}_i \cdot \underline{x}_i \right\rangle = \frac{1}{T} \int_0^T dt \frac{d}{dt} \left(\sum_i \underline{p}_i \cdot \underline{x}_i \right)$$

$$\rightarrow 0$$

$$T \rightarrow \infty$$

so ...

→ (First) Virial of system

$$2 \langle T \rangle = \left\langle \sum_i \frac{\partial U}{\partial x_i} \cdot x_i \right\rangle$$

Further, if $U = U(x_1, x_2, \dots, x_n)$

where $U(\alpha x_1, \alpha x_2, \dots, \alpha x_n) = \alpha^k U(x_1, x_2, \dots, x_n)$
 (scaling \leftrightarrow structure of power-law potentials \rightarrow i.e. h.o. $\rightarrow k=2$
 Coulomb $\rightarrow k=-1$)
 homogeneous function

$$\Rightarrow \boxed{2 \langle T \rangle = k \langle U \rangle}$$

but of course:

$$T + U = \langle T \rangle + \langle U \rangle = E$$

then $\left(\frac{k}{2} + 1\right) \langle U \rangle = E$

$$\boxed{\langle U \rangle = \frac{2}{k+2} E}, \quad \langle T \rangle = \frac{kE}{k+2}$$

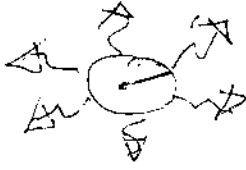
check: $k=2, \langle U \rangle = 1/2 E, \langle T \rangle = 1/2 E$ ✓

$k=-1, \langle T \rangle = -E \Rightarrow E < 0$ ✓ \Rightarrow bounded motion only if total energy negative (i.e. bound state)

Aside: simplest realization of negative specific heat 'paradox', c.e.

(R) \rightarrow consider 'blob' of self-gravitating matter

$$E \sim -1/R$$

if radiation  \rightarrow E decreases \rightarrow R decreases

$\therefore (-E)$ increases $\Rightarrow \langle T \rangle$ increases
 \rightarrow kinetic energy

but $\langle T \rangle \sim$ temperature, so have

cycle of: radiative cooling \Rightarrow temperature increases!

$$\Rightarrow c < 0 !!$$

specific heat

In the days before the discovery of nuclear fusion, this was thought to be what heated stars. Kelvin, in particular, was a proponent.

Now, proceeding to full virial theorem ...

→ Consider equations of motion

$$\frac{\partial}{\partial t} \underbrace{(\rho v_i)}_{\text{momentum}} = - \frac{\partial}{\partial x_j} \underbrace{T_{ij}}_{\text{full stress tensor}}$$

$$T_{ij} = \rho v_i v_j + \left(\rho + \frac{\underline{B}^2}{8\pi} \right) \delta_{ij} - \frac{B_i B_j}{4\pi} + \rho \phi \delta_{ij}$$

Now, recalling relation of v_i to $\frac{d}{dt}(\rho \underline{x})$
 \Rightarrow consider:

$$I_{ij} = \int d^3x \rho x_i x_j \quad (\sim \text{moment of inertia})$$

↳ Virial theorem is for tensor ...

and

$$\frac{d}{dt} I_{ij} = \int d^3x \frac{\partial \rho}{\partial t} x_i x_j$$

$$= - \int d^3x \frac{\partial}{\partial x_t} (\rho v_t) x_i x_j$$

integrating by parts assuming ρ compact (i.e. 'blob' of interest)

$$= \int d^3x [\rho x_i v_j + \rho x_j v_i]$$

so

$$\frac{d^2 I_{ij}}{dt^2} = \int d^3x \left[x_i \left(\frac{\partial}{\partial t} \rho v_j \right) + x_j \frac{\partial}{\partial t} (\rho v_i) \right]$$

but $\frac{\partial}{\partial t} (\rho v_i) = -\frac{\partial}{\partial x_k} T_{ik}$

\Rightarrow

$$\frac{d^2 I_{ij}}{dt^2} = -\int d^3x \left[x_i \frac{\partial T_{ij,t}}{\partial x_t} + x_j \frac{\partial T_{ji,t}}{\partial x_t} \right]$$

and integrating by parts, assuming $\left\{ \begin{array}{l} \text{compact blob,} \\ \text{no external} \\ \text{linkage} \end{array} \right.$

\Rightarrow

$$\frac{d^2 I_{ij}}{dt^2} = +\int d^3x \left[\delta_{ij,t} T_{j,t} + \delta_{j,t} T_{i,t} \right]$$

$$\frac{\partial x_i}{\partial x_t} = 0 \\ \text{unless } i=t$$

$$= +\int d^3x \left[T_{j,i} + T_{i,j} \right]$$

and as T_{ij} manifestly symmetric \Rightarrow

$$\frac{1}{2} \frac{d^2 I_{ij}}{dt^2} = +\int d^3x T_{ij}$$

$$T_{ij} = \rho v_i v_j + \underbrace{(\rho + \frac{B^2}{8\pi})}_{\text{energy density}} \delta_{ij} - \underbrace{\frac{B_i B_j}{4\pi}}_{\text{magnetic stress}}$$

— tensor virial theorem.

note unlike simple
pt particle example,
time dependence
remains.

Now, to make contact with notions of energy etc., useful to contract the tensor

$$I = I_{ij}i = \text{tr } I_{ij}$$

repeated
indexes
summed

to (V.T.) \Rightarrow

$$\begin{aligned} \text{tr } \frac{1}{2} \frac{d^2 I_{ij}}{dt^2} &= \frac{d^2}{dt^2} \left(\int d^3x \frac{\rho x^2}{2} \right) \\ &= \text{tr} \int d^3x \left[\rho v_i v_j + \left(\rho + \frac{\beta^2}{8\pi} \right) \delta_{ij} \right. \\ &\quad \left. - \frac{\beta_i \beta_j}{4\pi} + \rho \phi \delta_{ij} \right] \\ &= \int d^3x \left[\rho v^2 + 3 \left(\rho + \frac{\beta^2}{8\pi} \right) - \frac{\beta^2}{4\pi} + 3\rho\phi \right] \end{aligned}$$

$$\therefore I \equiv \int d^3x \rho x^2 / 2 \quad \Rightarrow$$

$$\boxed{\frac{d^2 I}{dt^2} = \int d^3x \left[\rho v^2 + 3\rho + \frac{\beta^2}{8\pi} + 3\rho\phi \right]}$$

\rightarrow Scalar Virial Theorem.

Now, first neglect self-gravitation \Rightarrow

$$\frac{d^2 I}{dt^2} = \frac{d^2}{dt^2} \left(\int d^3x \frac{\rho x^2}{2} \right)$$

$$= \int d^3x \left[\rho v^2 + 3p + B^2/8\pi \right]$$

Now \rightarrow can an isolated blob of MHD fluid confine itself? $?$

If 'self-confined' $\Rightarrow \frac{dI}{dt} \leq 0$

i.e. quiescent $\Rightarrow \dot{I}, \ddot{I} = 0$ $\frac{d^2 I}{dt^2} \leq 0$

stable $\Rightarrow \ddot{I} = -\Omega^2 I < 0$
pulsation

but have $\ddot{I} = \int d^3x \left[\rho v^2 + 3p + B^2/8\pi \right]$

so even if $v^2 = 0$ (no fluid motion on blob) \Rightarrow

$p > 0, B^2/8\pi > 0 \Rightarrow \ddot{I} > 0!$

\therefore No \rightarrow isolated blob can't confine itself.

More generally, noting that

$$E_V = \int d^3x \rho V^2 / 2$$

$$E_P = \int d^3x \frac{p}{\gamma-1} = \frac{3}{2} \int d^3x p \quad (\text{gas})$$

$$E_B = \int d^3x \frac{B^2}{8\pi}$$

can write scalar Virial theorem in form:

$$\frac{d^2 I}{dt^2} = 2 E_V + 2 E_P + E_B$$

simple relation in terms energies.

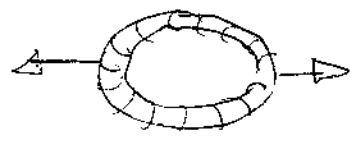
Aside: $\Rightarrow S_0$, isolated blob can't confine itself

\Rightarrow how is $\left\{ \begin{array}{l} \text{tokamak} \rightarrow B_T \text{ for } \left\{ \begin{array}{l} \text{stability; not} \\ \text{transport} \end{array} \right. \\ \text{or - better} \\ \text{macro-confinement} \\ \text{RFP} \rightarrow \text{weak external } B_T \text{ guide} \\ \text{(negligible)} \end{array} \right.$

confined $\uparrow \uparrow$ Confinement by wall is unacceptable ...

x

Answer: \rightarrow toroidal plasma tends to expand toroidally



\rightarrow held in place by $\left\{ \begin{array}{l} \text{conducting shell} \\ \text{(often undesirable)} \end{array} \right. \underline{\text{or}}$
"vertical field"

c.p.



\rightarrow additional external B_{Mag} to oppose toroidal expansion - vertical field

\rightarrow image currents in close-in conducting shell can do likewise

JET anecdote
re: vertical field failure ...

Now, retaining self-gravitation:

$$T_{ij} \Big|_{\text{gravity}} = \rho \phi \delta_{ij} = 2 \underbrace{\left(\frac{\rho \phi}{2} \right)}_{E_{\text{gravity}}} \delta_{ij}$$

to calculate:

$$\nabla^2 \phi = 4\pi G \rho$$

$$\Rightarrow \phi = -G \int d^3x' \frac{\rho(x')}{|x-x'|}$$

so

$$T_{ij} \Big|_{\text{gravity}} = T \Big|_{\text{gravity}} \delta_{ij}$$

 \Rightarrow

$$T = -\frac{G}{2} \int d^3x \int d^3x' \frac{\rho(x)\rho(x')}{|\underline{x}-\underline{x}'|}$$

$$= + E_{\text{gravitation}} = -E_g < 0$$

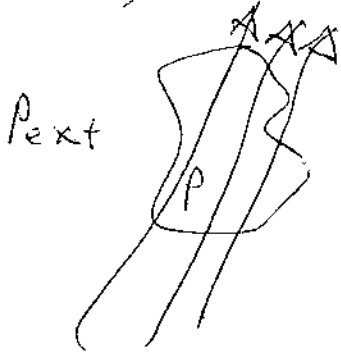
so scalar Virial theorem becomes, with gravity \Rightarrow

$$\frac{1}{2} \frac{d^2 I}{dt^2} = 2E_v + 2E_p - |E_g| + E_B$$

so with gravity, can have self-confining blob
(no surprise...)

This brings us to another application of Virial theorems, namely proto-stellar cloud collapse...

- now, consider a plasma cloud/blob



- mass M , radius R
- threaded by B
- pressure P external pressure P_0
- no bulk motion
- frozen flux

now, easy to show for $\vec{I} = 0$, $\vec{v} = 0$, must have:
surface terms

$$2E_p - |E_g| + E_B = \int dA \underbrace{P_{\text{ext}} \hat{x} \cdot \hat{n}}_{\substack{\downarrow \\ \text{external} \\ \text{pressure}}} - \int dA \underbrace{\hat{x} \cdot \underline{T}_B \cdot \hat{n}}_{\substack{\uparrow \\ \text{magnetic stress} \\ \text{thru surface} \\ \text{(threading fields)}}$$

Now, can estimate:

$$M = \int \rho dV \rightarrow \text{total mass}$$

$$E_p \approx C_s^2 M$$

$$|E_g| \approx \underbrace{\alpha}_{\substack{\downarrow \\ \text{form factor}}} \frac{GM^2}{R}$$

$$\text{For frozen flux, } \Phi \sim \pi R^2 B$$

so $E_B + \int dA \underline{x} \cdot \underline{I}_B \cdot \underline{\hat{n}} \sim \beta \bar{\Phi}^2 / R$

\Rightarrow have: (eliminating extraneous factors):

$$R^2 P_{\text{ext}} \sim \left(\frac{\beta \bar{\Phi}^2}{R} - \alpha \frac{GM^2}{R} + \frac{3}{2} C_s^2 M \right)$$

\rightarrow scalar virial theorem for cloud...

Now: $P_{\text{ext}} \sim \left(\frac{\beta \bar{\Phi}^2}{R^3} - \alpha \frac{GM^2}{R^3} + \frac{3}{2} \frac{C_s^2 M}{R^2} \right)$

\rightarrow if $\bar{\Phi}, G \rightarrow 0 \rightarrow$ need $P_{\text{int}} = P_{\text{ext}}$ for confinement...

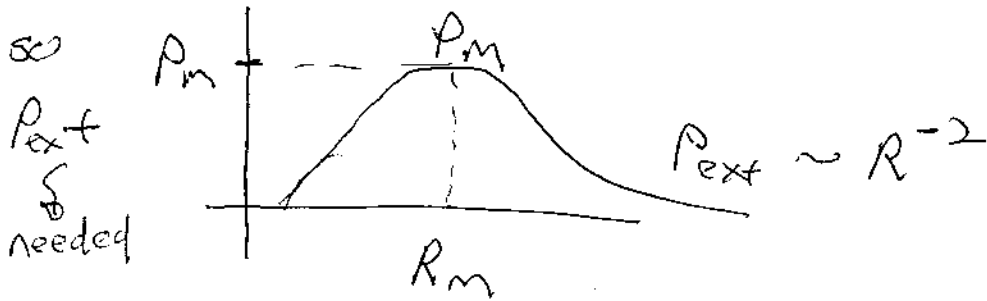
\rightarrow if $\bar{\Phi} = 0$

$$P_{\text{ext}} = -\alpha \frac{GM^2}{R^3} + \frac{3}{2} \frac{C_s^2 M}{R^2}$$

$$dP/dR = 0 \Rightarrow 3\alpha \frac{GM^2}{R^4} = \frac{3}{2} \frac{C_s^2 M}{R^3}$$

$$R_{\text{max}} = GM\alpha / C_s^2$$

$$\left[\text{Note: } \Rightarrow R_{\text{m}}^2 = \left(G\rho / C_s^2 \right)^{-1/2} \Rightarrow L_{\text{Jeans}}^2 \right]$$



- $\rho > \rho_{\text{max}} \rightarrow$ no equilibrium
- $R < R_{\text{max}} \rightarrow \rho_{\text{ext}}$ must decrease to maintain equilibrium \Rightarrow instability to gravitational collapse!

- $\bar{\Phi} \neq 0$ (magnetic field on ---) \rightarrow note immediately that magnetic support scales similarly to gravitational attraction

\Rightarrow

$$\rho_{\text{ext}} \sim \left[(\beta \bar{\Phi}^2 - \alpha GM^2) / R^3 + \frac{3}{2} \frac{c_s^2 M}{R^2} \right]$$

so key point is: $(\beta \bar{\Phi}^2 - \alpha GM^2) \lesssim 0$?!

$$\Rightarrow M < M_{\Phi} = \sqrt{\beta \alpha} \bar{\Phi} / c^{1/2}$$

$M < M_{\Phi} \rightarrow$ magnetically subcritical mass for gravitational collapse

$M > M_{\Phi} \rightarrow$ magnetically super-critical mass for collapse.

c.e. $M < M_{\Phi}$ \rightarrow repulsive effects $\left\{ \begin{array}{l} \text{field} \\ \text{thermal} \end{array} \right\}$ pressure always win
 $(M_{\Phi}^2 - M^2 > 0)$ \rightarrow no amount of external compression can induce indefinite contraction, IF flux remains frozen in

$M > M_{\Phi}$ \rightarrow sufficient external pressure/compression can induce gravitational collapse, even if flux frozen in.
 $(M_{\Phi}^2 - M^2 < 0)$

[Note: IF kinetic energy contribution, NL Alfvén waves can support cloud.]

For perspective, recall:

- (famous) Chandrasekhar Mass
 - $M > M_{\text{Chandra}} \rightarrow$ collapse
 - $M < M_{\text{Chandra}} \rightarrow$ no collapse.

M_{Chandra} derived for degenerate Fermi gas equations of state $\rightarrow \gamma = 4/3$, instead of $\gamma = 5/3$.

- of flux-freezing $\Rightarrow \frac{\Phi}{\rho R^3} \sim M$

$$\Rightarrow B \sim R^{-2} \Rightarrow B \sim \rho^{2/3}$$

$$\therefore B^2 \sim P_{\text{Mag}} \sim \rho^{4/3}$$

\Rightarrow if flux frozen, field obeys equation of state like Fermi gas

(i.e. flux freezing is akin to exclusion, albeit on field-lines-per-fluid-element)

\therefore an analogue to Chandrasekhar mass seems quite plausible

Aside: Chandrasekhar Limit - Simple Derivation
(c.f.: Shapiro, Teukolsky)

→ suppose: N Fermions in star of radius R
 $\therefore n_{\text{Fermion}} \sim N/R^3$

\therefore Vol./Fermion $\sim 1/n$ (Pauli exclusion)

$p \sim \hbar/\Delta x \sim \hbar n^{1/3}$ (Heisenberg Uncertainty)
 \downarrow
 Fermion Momentum

\Rightarrow Fermion energy (per Fermion) : $E_F = pc \sim \hbar c \frac{N^{1/3}}{R}$ (replaces: (i.e. thermal energy))

Gravitational Energy (per Fermion) : $E_{\text{grav}} \sim -\frac{GMm_b}{R}$ \downarrow Baryon mass

$$M \sim N m_B$$

Pressure \rightarrow electron
 Mass \rightarrow Baryon

$$\begin{aligned} \therefore E &= E_F + E_G \\ &= \frac{\hbar c N^{1/3}}{R} - \frac{GNm_B^2}{R} \end{aligned}$$

Note: $E = E_F + E_G$

$$= \frac{\hbar c N^{1/3}}{R} - \frac{GNM_B^2}{R}$$

$E > 0 \Rightarrow$ decrease E, E_F by increasing R .

but as $E_F \downarrow$, electrons non-relativistic,
 $\therefore E_F \sim 1/R^2 \rightarrow$ eqbm.

$E < 0 \Rightarrow$ decrease E without bound by
 decreasing $R \Rightarrow$ collapse.

\therefore eqbm: $\hbar c N^{1/3} = GNM_B^2$

$$N_{\text{Max}} = \left(\frac{\hbar c}{GNM_B^2} \right)^{3/2} \sim 2 \times 10^{57} \quad (\text{proton})$$

$\therefore M_{\text{Chandrasekhar}} = N_{\text{max}} M_B \sim 1.5 M_{\odot}$

→ Magnetic Helicity

- another conserved quantity in ideal MHD is magnetic helicity K

$$K = \int_V d^3x \underline{A} \cdot \underline{B}$$

V is taken to be the volume of a 'flux tube'.

- what, yet another invariant! Π

→ K is different \Rightarrow has topological interpretation

$$K = \int_V d^3x \underline{A} \cdot \underline{\nabla} \times \underline{A}$$

→ $\underline{x} \rightarrow -\underline{x}$ flips sign of K

→ K is a pseudo-scalar
i.e. has orientation or "handedness"...

Proceed via:

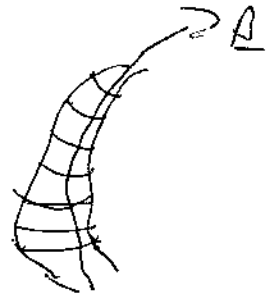
- show K conservation
- discuss interpretation of K
- comment on utility \Rightarrow Taylor Relaxation

N.B.: Important $\Rightarrow K$ is gauge invariant

i.e. if $\underline{A} \rightarrow \underline{A} + \underline{\nabla}\chi$

$$K \rightarrow K + \int_V d^3x \underline{\nabla} \cdot \underline{\kappa} \cdot \underline{B}$$

$$= K + \int_V d^3x \underline{\nabla} \cdot (\underline{B} \underline{\kappa})$$



$$= 0 \quad \text{to surface term.} \quad \left\{ \begin{array}{l} \underline{B} \cdot \underline{\hat{n}} = 0 \text{ on surface of} \\ \text{tube} \end{array} \right.$$

Now, consider a blob of MHD fluid in motion



can show $\frac{dK}{dt} =$

$$\underline{E} + \frac{\underline{v} \times \underline{B}}{c} = \eta \underline{J}$$

$$\underline{E} = -\frac{1}{c} \frac{\partial A}{\partial t} - \underline{\nabla} \phi$$

\Rightarrow

$$\frac{\partial \underline{A}}{\partial t} = \underline{v} \times \underline{\nabla} \times \underline{A} - c \underline{\nabla} \phi - c \eta \underline{J}$$

$$\frac{\partial \underline{B}}{\partial t} = -\underline{v} \cdot \underline{\nabla} \underline{B} + \underline{B} \cdot \underline{\nabla} \underline{v} - \underline{B} \underline{\nabla} \cdot \underline{v} + \eta \nabla^2 \underline{B}$$

$$\frac{dK}{dt} = \frac{d}{dt} \int_V d^3x (\underline{A} \cdot \underline{B})$$

$$= \int d^3x \left(\frac{d\underline{A}}{dt} \cdot \underline{B} + \underline{A} \cdot \frac{d\underline{B}}{dt} \right) + \int_V \underline{A} \cdot \underline{B} \frac{d}{dt} d^3x$$

$$\frac{dK}{dt} = \int d^3x \left(\frac{\partial A}{\partial t} \cdot \underline{B} + (\underline{v} \cdot \nabla A) \cdot \underline{B} + A \cdot \frac{\partial B}{\partial t} + A \cdot (\underline{v} \cdot \nabla B) \right) + \underline{A} \cdot \underline{B} \nabla \cdot \underline{v}$$

where $\frac{d}{dt} d^3x = \nabla \cdot \underline{v}$

i.e. $\frac{d}{dt} dV = \frac{d}{dt} d\underline{r} \cdot d\underline{l} + d\underline{r} \cdot \frac{d}{dt} d\underline{l}$
 $= -d\underline{l} \cdot \nabla \underline{v} \cdot d\underline{r} + (\underline{v} \cdot \nabla)(d\underline{r} \cdot d\underline{l}) + d\underline{l} \cdot \nabla \underline{v} \cdot d\underline{r}$

$= \nabla \cdot \underline{v} d^3x$ s.t. and $\underline{B} \cdot \underline{n}$ on surface of tube.

$$\frac{dK}{dt} = \int d^3x \left[(\underline{B} \cdot \underline{v} \times \underline{B} - c \underline{B} \cdot \nabla \underline{A} - c \underline{A} \cdot \nabla \underline{B}) \right]$$

$$+ \underline{A} \cdot \left(\nabla \times (\underline{v} \times \underline{B}) + \nabla \cdot ((\underline{A} \cdot \underline{B}) \underline{v}) + \underline{A} \cdot \nabla \underline{B} \right)$$

where $\underline{A} \cdot (\underline{v} \cdot \nabla \underline{B}) + \underline{B} \cdot (\underline{v} \cdot \nabla \underline{A}) + \underline{A} \cdot \underline{B} \nabla \cdot \underline{v} = \nabla \cdot (\underline{v} \underline{A} \cdot \underline{B})$

$$\frac{dK}{dt} = \int d^3x \left[\nabla \cdot ((\underline{A} \cdot \underline{B}) \underline{v}) + \nabla \cdot ((\underline{v} \times \underline{B}) \times \underline{A}) + (\underline{v} \times \underline{B}) \cdot (\nabla \times \underline{A}) \right]$$

$$- c \underline{A} \cdot \nabla \underline{B} - \nabla \cdot (\underline{A} \cdot \nabla \times \underline{A}) c$$

$$\Rightarrow \frac{dK}{dt} = \int d^3x \left\{ \underline{V} \cdot \left[(\underline{A} \cdot \underline{B}) \underline{V} + (\underline{V} \times \underline{B}) \times \underline{A} + c\mu (\underline{A} \times \underline{J}) \right] - c\mu \underline{J} \cdot \underline{B} - c\mu \underline{V} \cdot \underline{B} \right\}$$

$$= \int dS \cdot \left[(\underline{A} \cdot \underline{B}) \underline{V} + (\underline{V} \times \underline{B}) \times \underline{A} + c\mu \underline{A} \times \underline{J} \right]$$

$$- 2 \int d^3x \left[c\mu \underline{J} \cdot \underline{B} \right]$$

$$= \int dS \cdot \left[\cancel{(\underline{A} \cdot \underline{B}) \underline{V}} - \cancel{(\underline{A} \cdot \underline{B}) \underline{V}} + \underbrace{(\underline{A} \cdot \underline{V}) \underline{B}}_{\underline{B} \cdot \underline{n} = c, \text{ on tube}} \right] - c\mu \int dS \cdot \underline{J} \times \underline{A}$$

$$- 2c\mu \int d^3x (\underline{J} \cdot \underline{B})$$

$$= - \int c\mu dS \cdot \left[\underline{B} \cdot \underline{A} - \cancel{\underline{A} \cdot \underline{B}} \right] - 2c\mu \int d^3x \underline{J} \cdot \underline{B}$$

$$= - 2c\mu \int d^3x (\underline{J} \cdot \underline{B})$$

\Rightarrow have shown:

$$\boxed{\frac{dK}{dt} = - 2c\mu \int d^3x (\underline{J} \cdot \underline{B})}$$

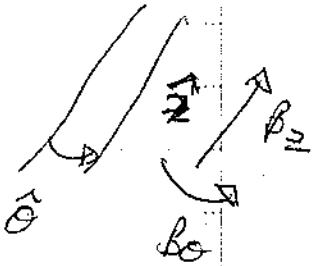
and clearly! $\frac{dK}{dt} \rightarrow 0$ as $\eta \rightarrow 0$
(non-singular \underline{J})

Magnetic Helicity is conserved in ideal MHD.

→ Magnetic Helicity conserved, but what does it mean?

- helicity is non-trivial \Rightarrow more than just helical field lines.

interesting to note: $g(r) = \frac{r B_z}{R B_0(r)} = \frac{1}{R u(r)}$



$u(r) = \frac{B_\theta(r)}{r B_z} \rightarrow$ Field line pitch.

cylindrical plasma $\Rightarrow \underline{B} = \underline{B}(r)$

Now, $A_\theta = \frac{1}{r} \int_0^r r' B_z dr'$

$A_z = - \int_0^r B_\theta dr'$

$$\text{so } \underline{A} \cdot \underline{B} = \frac{B_\theta}{r} \int_0^r B_z dr - B_z \int_0^r B_\theta dr$$

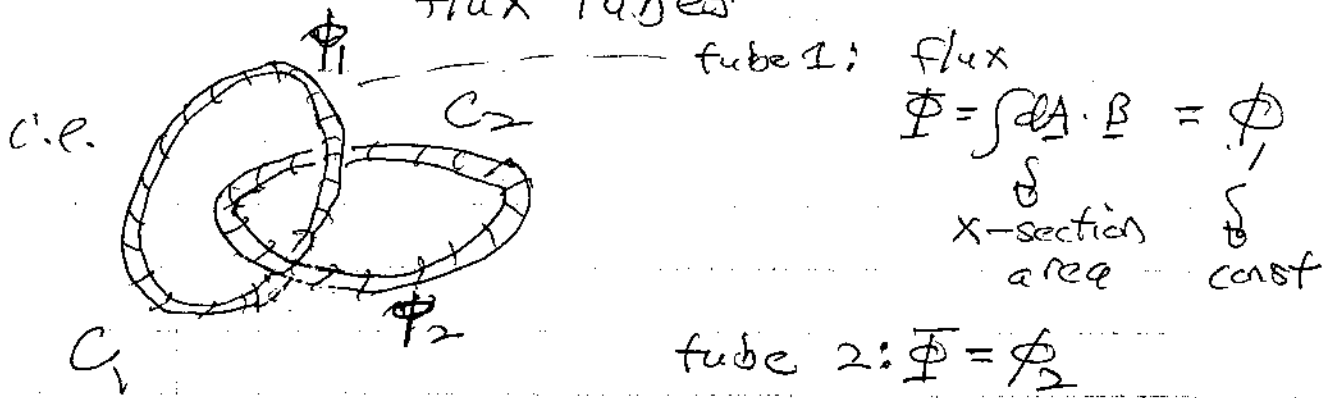
$$= \mu B_z \int_0^r \frac{B_\theta}{\mu} dr - B_z \int_0^r B_\theta dr$$

$$\underline{A} \cdot \underline{B} = B_z \left[\mu \int_0^r \frac{B_\theta}{\mu} dr - \int_0^r B_\theta dr \right]$$

= 0 for constant μ

∴ non-zero helicity requires $\mu = \mu(r)$
 i.e. - pitch varies with radius
 \Rightarrow magnetic shear

- physically \rightarrow helicity means self-linkage of flux tubes



field in loops, only

Now, for volume V_1 of tube 1

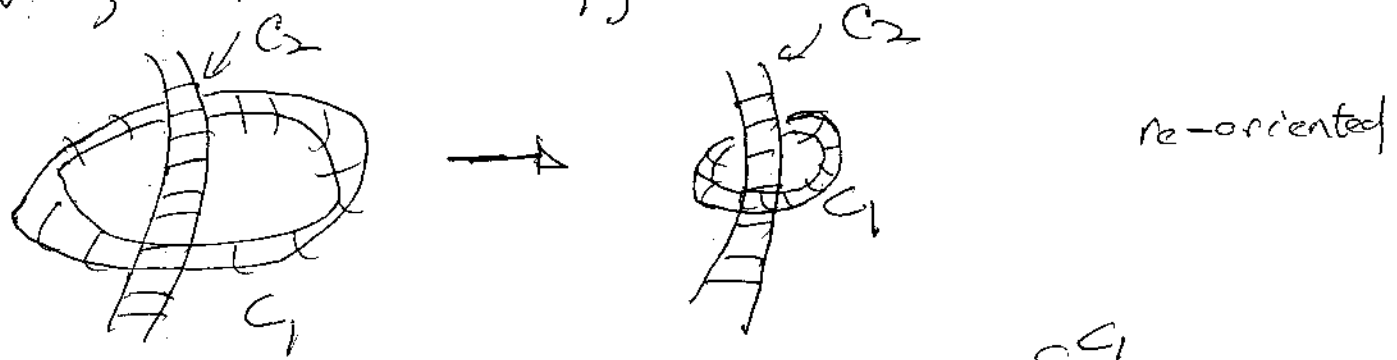
$$K = \int_{V_1} \underline{A} \cdot \underline{B} \, d^3x = \oint_{C_1} d\ell \int_{S_1} \underline{A} \cdot \underline{B}$$

$\left\{ \begin{array}{l} \text{along} \\ \text{loop} \end{array} \right.$
 $\left\{ \begin{array}{l} \text{X-section} \\ \text{area} \end{array} \right.$

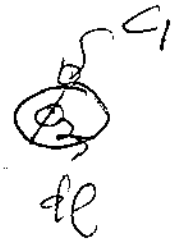
$$= \oint_{C_1} \underline{A} \cdot d\ell \int_{S_1} \underline{B} \cdot \underline{\hat{n}} \, dA$$

$$= \oint_{C_1} \oint_{S_1} \underline{A} \cdot d\ell$$

Now, can shrink C_1 , as no field outside loops



→ in x section:



but $\int_{C_1} \underline{A} \cdot d\ell = \int_{A \text{ enclosed}} \underline{B} \cdot dS = \Phi_2$

so... $k_1 = \phi_1 \phi_2 \rightarrow$ product of fluxes

similarly $k_2 = \phi_2 \phi_1$

$$\therefore k = 2\phi_1 \phi_2$$

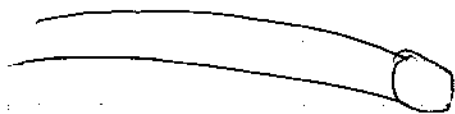
if n windings $k = k_1 + k_2 = \pm 2n\phi_1 \phi_2$

\Rightarrow helicity is measure of self-linkage of magnetic configuration.

Why care \rightarrow Taylor Conjecture (1974)
(J.B. Taylor)

- in magnetic confinement, of great interest to determine how fields, currents self-organize

- RFP



\rightarrow toroid

\rightarrow toroidal current

well fit by

$$B_z = B_0 J_0(\alpha r)$$

$$B_\theta = B_0 J_1(\alpha r)$$

$$\underline{J} \times \underline{B} = 0$$

\underline{B}

force free

\Rightarrow why so robust? especially since RFP so turbulent

- Taylor conjectured conservation of magnetic helicity constrains relaxation to force-free state.

Key Point - helicity conserved in flux tubes, to ∞
 - toroidal plasma \rightarrow many small tubes



etc.

- recall Sweet-Parker model:
 magnetic reconnection / resistive dissipation effective on small scales.

\Rightarrow Taylor Conjecture: At finite η , helicity of small tubes dissipated but global helicity conserved.

i.e.

$$\int_{\text{plasma volume}} \underline{A} \cdot \underline{B} \, d^3x = K_0 \rightarrow \text{conserved.}$$

\therefore Taylor conjectured that actual magnetic configuration could be explained by minimum principle:

$$\delta \left[\int d^3x \frac{B^2}{8\pi} + \lambda \int d^3x \underline{A} \cdot \underline{B} \right] = 0$$

i.e. minimize magnetic energy subject to constraint of conserved global helicity,

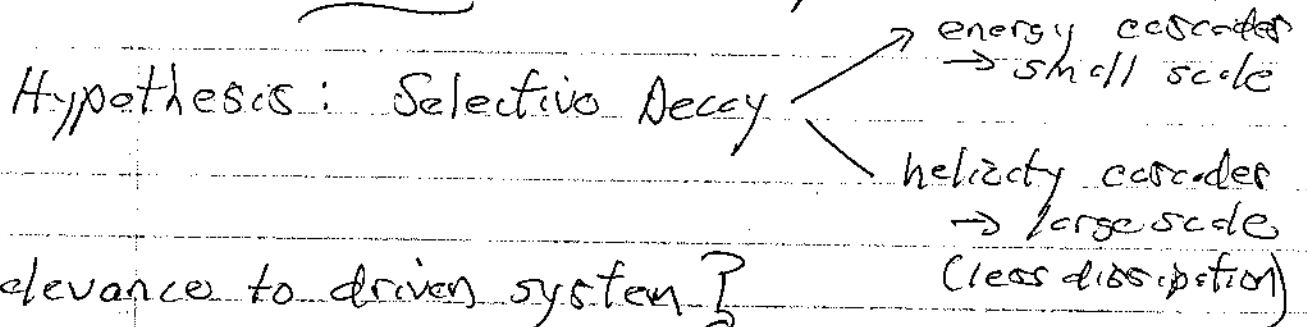
Comments:

→ it works! - indeed amazingly well - for

RFPs, spheromaks, etc. Departures only recently being discovered

→ inspired idea of helicity injection as way to maintain configurations.

→ it is a conjecture → no proof.



- relevance to driven system? i.e. in real RFP, transformer on

→ dynamics? - how does relaxation occur

→ more in discussion of kinks, tearing.